

#### **Features**

- 3W Output at 10% THD with a 4Ω Load and 5V Power Supply
- Filterless, Low Quiescent Current and Low EMI
- Low THD+N
- 64-Step DC Volume Control from -75dB to +24dB
- Superior Low Noise
- Efficiency up to 89%
- Short Circuit Protection
- Thermal Shutdown
- Few External Components to Save the Space and Cost
- Pb-Free Package

# **Applications**

- LCD Monitors/TV Projectors
- Notebook Computers
- Portable Speakers
- Portable DVD Players, Game Machines
- Cellular Phones/Speaker Phones

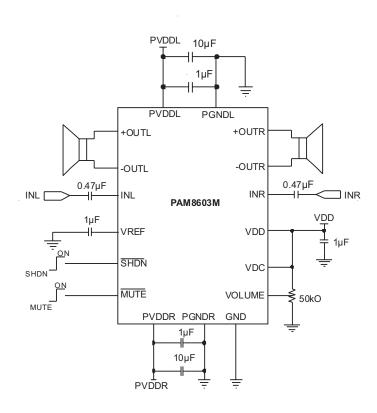
### **General Description**

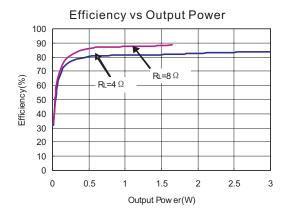
The PAM8603M is a 3W, sterero, class-D audio amplifier with DC volume control. It offers low THD+N, allowing it to produce high-quality sound reproduction. The new filterless architecture allows the device to drive the speaker directly, requiring no low-pass output filters, which saves the system cost and PCB area.

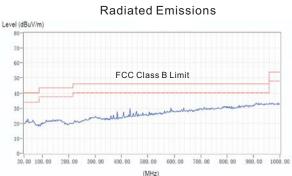
With the same numbers of external components, the efficiency of the PAM8603M is much better than class-AB cousins. It can extend the battery life thus ideal for portable applications.

The PAM8603M is available in SSOP-24 and SOP-18 packages.

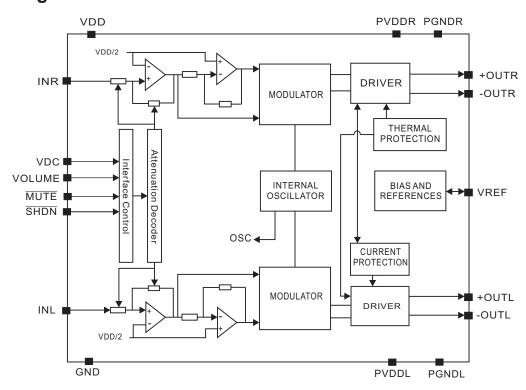
# **Typical Application Circuit**



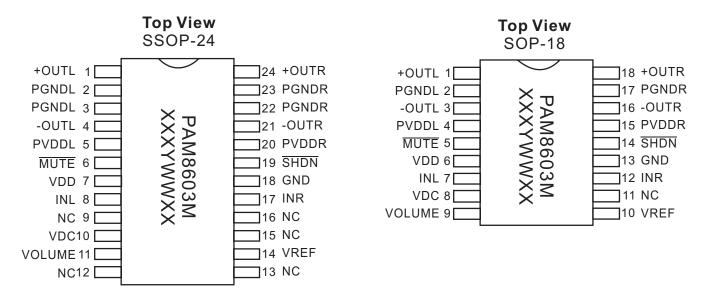




### **Block Diagram**



# Pin Configuration & Marking Information



X: Internal Code

Y: Year WW: Week



# **Pin Descriptions**

Pin Name	SSOP-24	SOP-18	Description
+OUTL	1	1	Left Channel Positive Output
PGNDL	2,3	2	Left Channel Power GND
-OUTL	4	3	Left Channel Negative Output
PVDDL	5	4	Left Channel Power Supply
MUTE	6	5	Mute Control Input (active low)
VDD	7	6	Analog Power Supply
INL	8	7	Left Channel Input
NC	9, 12,13,15,16	11	No Connect
VDC	10	8	Analog reference for gain control section
VOLUME	11	9	DC volume control to set the gain of Class-D
VREF	14	10	Internal analog reference, connect a bypass capacitor from VREF to GND
INR	17	12	Right Channel Input
GND	18	13	Analog Ground
SHDN	19	14	Shutdown Control Input(active low)
PVDDR	20	15	Right Channel Power Supply
-OUTR	21	16	Right Channel Negative Output
PGNDR	22,23	17	Right Channel Power GND
+OUTR	24	18	Right Channel Positive Output

# **Absolute Maximum Ratings**

These are stress ratings only and functional operation is not implied. Exposure to absolute maximum ratings for prolonged time periods may affect device reliability. All voltages are with respect to ground.

Supply Voltage6.6V	Maximum Junction Temperature150°C
Input Voltage0.3V to V <sub>DD</sub> +0.3V	Storage Temperature65°C to 150°C
	Soldering Temperature300°C, 5sec

# **Recommended Operating Conditions**

Supply Voltage Range2.8V to 5.5V	Junction Temperature Range40°C to 125°C
Max. Supply Voltage (for Max. duration of	Ambient Temperature Range40°C to 85°C
30 minutes)6.4V	

### **Thermal Information**

Parameter	Symbol	Package	Maximum	Unit
Thermal Resistance (Junction to Ambient)	Δ	SSOP-24	96	°C/W
Thermal Resistance (Junction to Ambient)	$ heta_{JA}$	SOP-18	70	°C/W
Thermal Begintance (Junetica to Cocc)	$\theta_{ extsf{Jc}}$	SSOP-24	18	°C/W
Thermal Resistance (Junction to Case)		SOP-18	16	°C/W



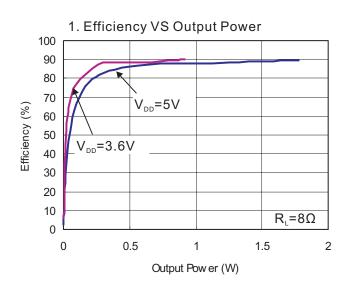
### **Electrical Characteristic**

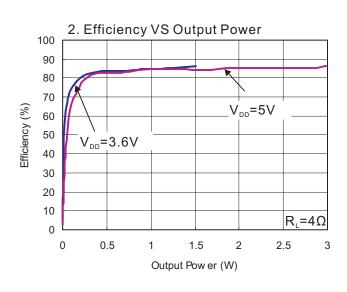
 $V_{DD}$ =5V, Gain=20dB,  $T_A$ =25°C, unless otherwise noted.

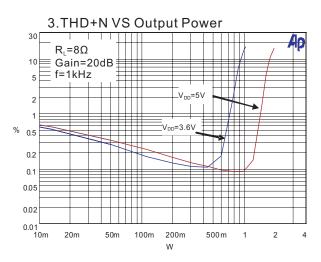
Symbol	Parameter	Test Conditions		MIN	TYP	MAX	UNIT
$V_{DD}$	Supply Voltage			2.8		5.5	V
		THD+N=10%, f=1kHz,R <sub>1</sub> =4Ω	V <sub>DD</sub> =5.0V	2.85	3.2		W
		1 ND+N-10%, 1-1KN2,R <sub>L</sub> -492	V <sub>DD</sub> =3.6V	1.55	1.8		
		TUD:N: 40/ 5 4111 D. 40	V <sub>DD</sub> =5.0V	2.35	2.6		W
Po	Output Power	THD+N=1%, f=1kHz, $R_L$ =4 $\Omega$	V <sub>DD</sub> =3.6V	1.25	1.5		
PO	Output Power	TUD:N=400/ 5-41-11- D =00	V <sub>DD</sub> =5.0V	1.55	1.8		W
		THD+N=10%, f=1kHz,R <sub>L</sub> =8 $\Omega$	V <sub>DD</sub> =3.6V	0.75	0.9		VV
		THD+N=1%,f=1kHz,R <sub>L</sub> =8Ω	V <sub>DD</sub> =5.0V	1.15	1.4		W
		111D 114-170,1-1K112,1X[-052	V <sub>DD</sub> =3.6V	0.5	0.72		VV
		$V_{DD}$ =5.0V,Po=0.5W,R <sub>L</sub> =8 $\Omega$	f=1kHz		0.15	0.3	%
THD+N	Total Harmonic	$V_{DD}$ =3.6V,Po=0.5W,R <sub>L</sub> =8 $\Omega$	I – IKI IZ		0.11	0.25	/0
ТПОТІ	Distortion Plus Noise	$V_{DD}$ =5.0V,Po=1W,R <sub>L</sub> =4 $\Omega$	f=1kHz		0.15	0.3	%
		$V_{DD}$ =3.6V,Po=1W,R <sub>L</sub> =4 $\Omega$	I – IKI IZ		0.11	0.25	70
PSRR	Power Supply Ripple	V <sub>DD</sub> =5.0V, Inputs ac-grounded	f=100Hz		-59	-50	- dB
PORK	Rejection	V <sub>DD</sub> =3.0 V, Inputs ac-grounded	f=1kHz		-58	-50	
Cs	Crosstalk	$V_{DD}$ =5V,Po=0.5W, $R_L$ =8 $\Omega$ ,f=1kHz			-95	-80	dB
SNR	Signal-to-noise ratio	$V_{DD}$ =5V, $Vo_rms=1V$ , f=1kHz		85	98		dB
Vn	Output noise	V <sub>DD</sub> =5V, Inputs ac-grounded	A-weighting		75	150	μV
V11	Output Holde	with Cin=0.47μF	No A-weighting		120	300	
Dyn	Dynamic range	V <sub>DD</sub> =5.0V, THD=1%, f=1kHz		90	102		dB
η	Efficiency	R <sub>L</sub> =8Ω, THD=10%	f=1kHz	85	89		- %
'1	Lindericy	$R_L$ =4 $\Omega$ , THD=10%	I – IKI IZ	80	85		
I <sub>Q</sub>	Quiescent Current	V <sub>DD</sub> =5V	No load		13.5	20	mA
iQ	Quicocont Ourient	V <sub>DD</sub> =3.6V	140 1044		8.5	15	IIIA
I <sub>MUTE</sub>	Muting Current	$V_{DD}$ =5.0V, $V_{MUTE}$ =0.3V			2.7	5	mA
I <sub>SD</sub>	Shutdown Current	$V_{DD}$ =2.5V to 5.5V, $V_{SD}$ =0.3V				1	μΑ
Rdson	Static Drain-to-source	I <sub>DS</sub> =500mA,Vgs=5V	PMOS		240	500	mΩ
TCGSOIT	On-state Resistor	Resistor			180	350	11152
fsw	Switching Frequency	V <sub>DD</sub> =3V to 5V		200	260	300	kHz
Vos	Output Offset Voltage	Vin=0V, V <sub>DD</sub> =5V			10	50	mV
V <sub>IH</sub>	SD/MUTE Input High	V <sub>DD</sub> =5V			1.45		V
V <sub>IL</sub>	SD/MUTE Input Low	V <sub>DD</sub> =5V			0.65		V
ОТР	Over Temperature Protection	No Load, Junction Temperature, V <sub>DD</sub> =5V			135		°C
ОТН	Over Temperature Hysterisis	1			30		

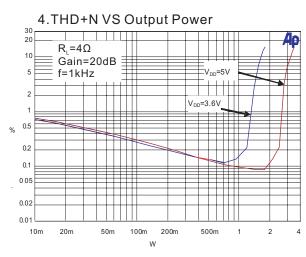


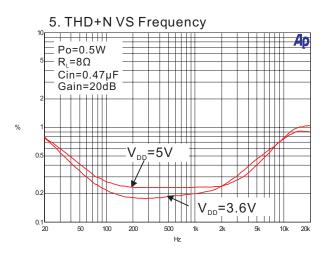
# **Typical Operating Characteristics** (T<sub>A</sub>=25°C)

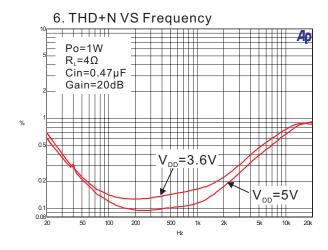






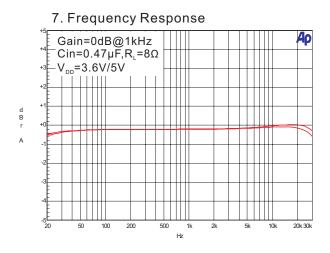


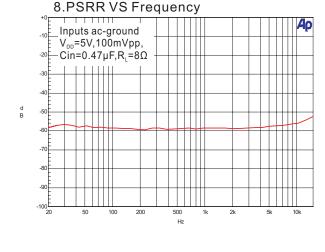


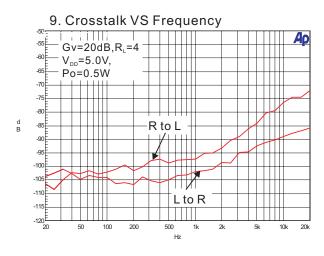


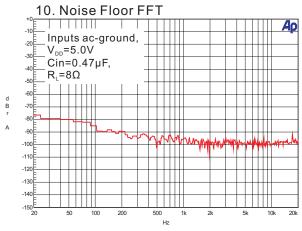


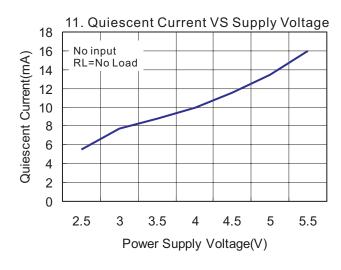
# **Typical Operating Characteristics**(T<sub>A</sub>=25°C)

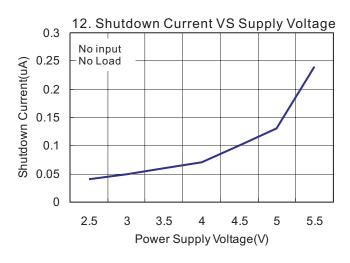






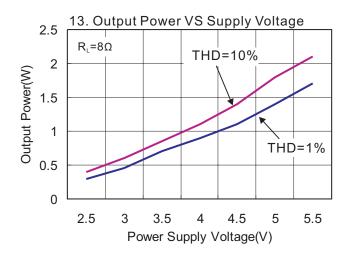


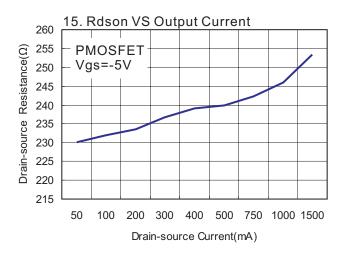


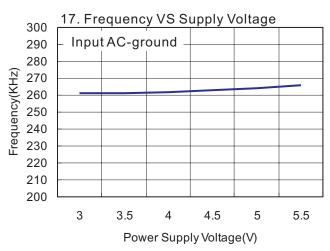


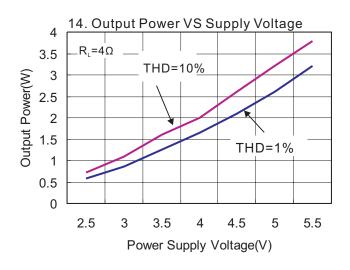


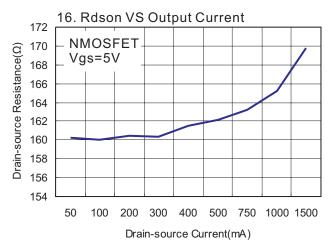
# **Typical Operating Characteristics** (T<sub>A</sub>=25°C)











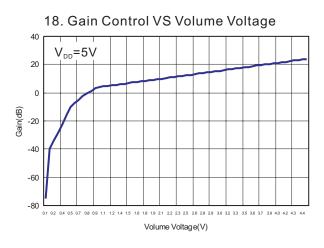




Table 1. DC Volume Control

STEP	Gain (dB)	STEP	Gain (dB)
0	-75	32	11.6
1	-40	33	12
2	-34	34	12.4
3	-28	35	12.8
4	-22	36	13.2
5	-16	37	13.6
6	-10	38	14
7	-7.5	39	14.4
8	-5	40	14.8
9	-2.5	41	15.2
10	0	42	15.6
11	1.5	43	16
12	3	44	16.4
13	4	45	16.8
14	4.4	46	17.2
15	4.8	47	17.6
16	5.2	48	18
17	5.6	49	18.4
18	6	50	18.8
19	6.4	51	19.2
20	6.8	52	19.6
21	7.2	53	20
22	7.6	54	20.4
23	8	55	20.8
24	8.4	56	21.2
25	8.8	57	21.6
26	9.2	58	22
27	9.6	59	22.4
28	10	60	22.8
29	10.4	61	23.2
30	10.8	62	23.6
31	11.2	63	24

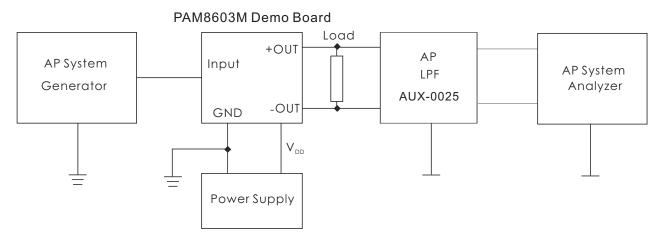
# **PAM8603M**

### 3W Filterless Stereo Class-D Audio Amplifier with DC Volume Control

# **Application Notice**

- 1. When the PAM8603M works with LC filters, it should be connected with the speaker before it is powered on, otherwise it will be damaged easily.
- 2. When the PAM8603M works without LC filters, it's better to add a ferrite chip bead at the outgoing line of speaker to suppress the possible electromagnetic interference.
- 3. The input signal should not be too high. If too high, it will cause the clipping of output signal when increasing the volume. Because the DC volume control of the PAM8603M has big gain, it will make the device damaged.
- 4. When testing the PAM8603M without LC filters by using resistor instead of speaker as the output load, the test results, e.g. efficiency, will be worse than those using speaker as load.

### **Test Setup for Performance Testing**



#### **Notes**

- 1. The AP AUX-0025 low pass filter is necessary for class-D amplifier measurement done by AP analyzer.
- 2. Two 22µH inductors are used in series with load resistor to emulate the small speaker for efficiency measurement.



### **Application Information**

#### **Mute Operation**

The MUTE pin is an input for controlling the output state of the PAM8603M. A logic low on this pin disables the outputs, and a logic high enables the outputs. This pin may be used as a quick disable or enable of the outputs without a volume fade. Quiescent current is listed in the electrical characteristic table. The MUTE pin can be left floating due to the internal pull-up.

For better power-off pop performance, the amplifier should be placed in the mute mode prior to removing the power supply.

#### **Shutdown Operation**

In order to reduce power consumption while not in use, the PAM8603M contains shutdown circuitry to turn off the amplifier's bias circuitry. The amplifier is turned off when logic low is placed on the SHDN pin. By switching the SHDN pin connected to GND, the PAM8603M supply current draw will be minimized in idle mode. The SHDN pin can be left floating due to the internal pull-up.

#### **Power Supply Decoupling**

The PAM8603M is a high performance CMOS audio amplifier that requires adequate power supply decoupling to ensure the output THD and PSRR as low as possible. Power supply decoupling affects low frequency response. Optimum decoupling is achieved by using two capacitors of different types that target different noise on the power supply leads. For higher frequency transients, spikes, or digital hash on the line, a good low equivalent-series resistance (ESR) ceramic capacitor, typically 1.0µF, placed as close as possible to the device VDD terminal works best. For filtering lower-frequency noise signals, a large capacitor of 10µF (ceramic) or greater placed near the audio power amplifier is recommended.

#### Input Capacitor (C<sub>i</sub>)

Large input capacitors are both expensive and space hungry for portable designs. Clearly, a certain sized capacitor is needed to couple in low frequencies without severe attenuation. But in many cases the speakers used in portable systems, whether internal or external, have little ability to reproduce signals below 100Hz to 150Hz. Thus, using a large input capacitor may not increase actual system performance. In this

case, input capacitor  $(C_i)$  and input resistance  $(R_i)$  of the amplifier form a high-pass filter with the corner frequency determined equation below,

$$f_C = \frac{1}{2\pi R_i C}$$

In addition to system cost and size, click and pop performance is affected by the size of the input coupling capacitor,  $C_{\rm i}$ . A larger input coupling capacitor requires more charge to reach its quiescent DC voltage (nominally 1/2  $V_{\rm DD}$ ). This charge comes from the internal circuit via the feedback and is apt to create pops upon device enable. Thus, by minimizing the capacitor size based on necessary low frequency response, turn-on pops can be minimized.

### Analog Reference Bypass Capacitor (C<sub>BYP</sub>)

The Analog Reference Bypass Capacitor ( $C_{\mbox{\scriptsize BYP}}$ ) is the most critical capacitor and serves several important functions. During start-up or recovery from shutdown mode,  $C_{\mbox{\scriptsize BYP}}$  determines the rate at which the amplifier starts up. The second function is to reduce noise produced by the power supply coupling in the output drive signal. This noise is from the internal analog reference to the amplifier which appears as degraded PSRR and THD+N.

A ceramic bypass capacitor ( $C_{\text{BYP}}$ ) of 0.47 $\mu$ F to 1.0 $\mu$ F is recommended for the best THD and noise performance. Increasing the bypass capacitor reduces clicking and popping noise from power on/off and entering and leaving shutdown.

#### Under Voltage Lock-out (UVLO)

The PAM8603M incorporates circuitry to detect low supply voltage. When the supply voltage drops to 1.8V or below, the PAM8603M outputs are disable. The device resumes to normal functional once  $V_{\text{DD}} \geqslant 2.0\text{V}$ .

### **Short Circuit Protection (SCP)**

The PAM8603M has short circuit protection circuitry on the outputs to prevent the device from damage when output-to-output or output-to-GND short. When a short circuit is detected on the outputs, the outputs are disable immediately. If the short was removed, the device activates again.



#### **Over Temperature Protection**

Thermal protection on the PAM8603M prevents the device from damage when the internal die temperature exceeds 135°C. There is a 15 degree tolerance on this trip point from device to device. Once the die temperature exceeds the thermal set point, the device outputs are disabled. This is not a latched fault. The thermal fault is cleared once the temperature of the die is reduced by 30°C. This large hysteresis will prevent motor boating sound well. The device begins normal operation at this point without external system interaction.

# How to Reduce EMI (Electro Magnetic Interference)

A simple solution is to put an additional capacitor  $1000\mu F$  at power supply terminal for power line coupling if the traces from amplifier to speakers are short (<20cm).

Most applications require a ferrite bead filter as shown at Figure 3. The ferrite filter reduces EMI of around 1 MHz and higher. When selecting a ferrite bead, choose one with high impedance at high frequencies, and low impedance at low frequencies (MH2012HM221-T).

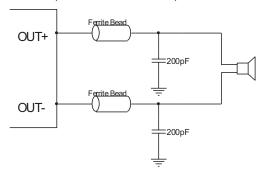
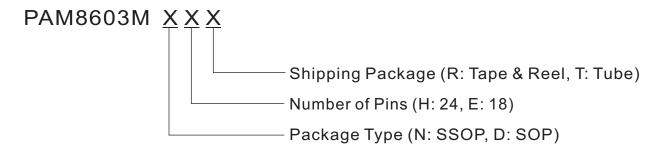


Figure 3: Ferrite Bead Filter to Reduce EMI

#### **PCB Layout Guidelines Grounding**

At this stage it is paramount to notice the necessity of separate grounds. Noise currents in the output power stage need to be returned to output noise ground and nowhere else. Were these currents to circulate elsewhere, they may get into the power supply, the signal ground, etc, even worse, they may form a loop and radiate noise. Any of these cases results in degraded amplifier performance. The logical returns for the output noise currents associated with Class-D switching are the respective PGND pins for each channel. The switch state diagram illustrates that PGND is instrumental in nearly every switch state. This is the perfect point to which the output noise ground trace should return. Also note that output noise ground is channel specific. A twochannel amplifier has two seperate channels and consequently must have two seperate output noise ground traces. The layout of the PAM8603M offers separate PGND connections for each channel and in some cases each side of the bridge. Output noise grounds must be tied to system ground at the power exclusively. Signal currents for the inputs, reference, etc need to be returned to guite ground. This ground is only tied to the signal components and the GND pin, and GND then tied to system ground.

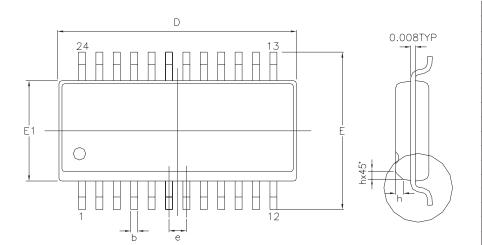
# **Ordering Information**



Part Number	Marking	Package Type	MOQ/Shipping Package	
PAM8603MNHR	PAM8603M	SSOP-24	2,500 Units/Tape & Reel	
17 WOOODWIN II Y	XXXYWWLL	000. 2.		
PAM8603MDER	PAM8603M	SOP-18	1,000 Units/Tape & Reel	
	XXXYWWLL	301 -10		
PAM8603MDET	PAM8603M	SOP-18	40 Units/Tube	
FAMOUSMDET	XXXYWWLL	301-10		

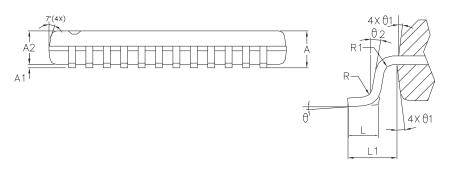
# **Outline Dimension**

# SSOP-24



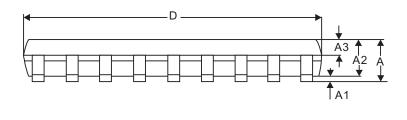
SYMBOLS	MIN.	NOM.	MAX.
А	0.053	0.061	0.069
A1	0.004	-	0.010
A2	0.049	0.057	0.065
b	0.008	0.010	0.012
D	0.335	0.341	0.347
E	0.228	0.236	0.244
E1	0.150	0.154	0.158
е	-	0.025	_
L	0.016	0.033	0.050
L1		ĒF	
R	0.003	-	-
R1	0.003	-	-
h	0.010	0.015	0.020
θ	0,	4*	8*
θ1	5°	10°	15°
θ2	0.	_	_

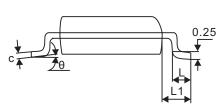
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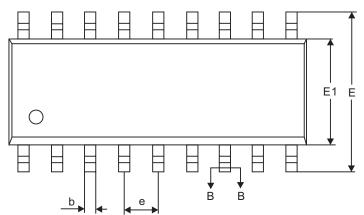


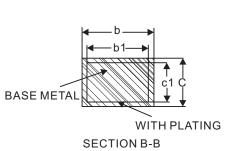
# **Outline Dimension**

# **SOP-18**









SYMBOL	MILLIMETER				
STIVIBOL	MIN NOM		MAX		
А	-	-	2.70		
A1	0.08	0.18	0.30		
A2	2.10	2.30	2.50		
A3	0.92	1.02	1.12		
b	0.35	-	0.44		
b1	0.34	0.37	0.39		
С	0.26	-	0.31		
c1	0.24	0.25	0.26		
D	11.25	11.45	11.76		
Е	10.00	10.30	10.64		
E1	7.30	7.50	7.70		
е	1.27BSC				
L	0.70	0.85	1.00		
L1	1.40BSC				
θ	0°	-	8°		